

Synchronization in Power Networks and in Non-uniform Kuramoto Oscillators

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Intro: Transient Stability in Power Networks

The New York Times

THE BLACKOUT OF 2003: Failure Reveals Creaky System, Experts Believe 8/15/2003



Energy is one of the top three national priorities [B. Obama, '09]

Expected additional synergetic effects in future "smart grid":



- ⇒ increasing complexity and renewable stochastic power sources
- ⇒ increasingly many transient disturbances to be detected and rejected



Transient Stability: Generators have to maintain synchronism in presence of large transient disturbances such as faults or loss of

- transmission lines and components,
- generation or load.

Intro: Transient Stability in Power Networks

"The vast North American power grid is the largest and most complex machine engineered by humankind." [P. Kundur '94, V. Vittal '03, ...]



Quick facts about the power grid:

- large-scale, complex, and nonlinear
- ⇒ various dynamic phenomena and instabilities
- 100 years old and operating at its capacity limits
- ⇒ increasing number of blackouts: New England '03, Italy '03, Brazil '09

Intro: Transient Stability Analysis in Power Networks

Mathematical model of a power network:

- swing equation for generator i :

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + P_{mi} - P_{ei}$$

$\theta(t)$ is measured w.r.t. a 60Hz rotating frame

- network-preserving model leads to DAEs
- network-reduction model leads to ODEs with reduced admittance matrix $Y_{ij} = |Y_{ij}| e^{i(\frac{\pi}{2} - \varphi_{ij})}$

$$P_{ei} = E_i^2 G_{ii} + \sum_{j \neq i} E_i E_j |Y_{ij}| \sin(\theta_i - \theta_j + \varphi_{ij})$$

Classic model considered in transient stability analysis:

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$



reduce network to its active nodes



Mathematical model of a power network:

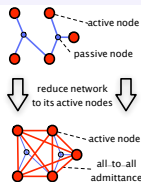
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- network-preserving model leads to **DAEs**
- network-reduction model leads to **ODEs** with reduced admittance matrix $Y_{ij} = |Y_{ij}| e^{i(\frac{\pi}{2} - \varphi_{ij})}$

$$P_{ei} = E_i^2 G_{ii} + \sum_{j \neq i} E_j E_i |Y_{ij}| \sin(\theta_i - \theta_j + \varphi_{ij})$$



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Transient stability and synchronization:

synchronization in presence of transient network disturbances

Classic analysis methods: Hamiltonian arguments

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i - \nabla_i U(\theta)^T$$

Energy function analysis, (extended) invariance principle, analysis of reduced gradient flow [N. Kakimoto et al. '78, H.-D. Chiang et al. '94]

$$\dot{\theta}_i = -\nabla_i U(\theta)^T$$

Key objective: compute domain of attraction via numerical methods

Classic model considered in transient stability analysis:

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

Transient stability and synchronization:

- frequency equilibrium: $(\dot{\theta}_i, \ddot{\theta}_i) = (0, 0)$ for all i
- synchronous equilibrium: $\theta_i - \theta_j$ bounded & $\dot{\theta}_i - \dot{\theta}_j = 0$ for all $\{i, j\}$

Classic problem setup in transient stability analysis:

- power network in stable frequency equilibrium
- transient network disturbance and fault clearance
- stability analysis of a new frequency equilibrium in post-fault network

More general synchronization problem:

synchronization in presence of transient network disturbances

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Classic model considered in transient stability analysis:

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

Transient stability and synchronization:

synchronization in presence of transient network disturbances

Classic analysis methods: Hamiltonian arguments

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i - \nabla H_i(\theta)^T \rightsquigarrow \dot{\theta}_i = -\nabla_i U(\theta)^T$$

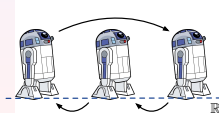
⇒ **Open problem** [D. Hill and G. Chen '06]: power sys \rightsquigarrow network:

transient stability, performance, and robustness of a power network
underlying network topology, parameters, and state

Consensus protocol in \mathbb{R}^n :

$$\dot{x}_i = - \sum_{j \neq i} a_{ij} (x_i - x_j)$$

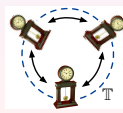
- n identical **agents** with state variable $x_i \in \mathbb{R}$
- **graph** with globally reachable node and weights $a_{ij} > 0$
- **objective** is state agreement: $x_i(t) - x_j(t) \rightarrow 0$
- **application**: social networks, computer science, systems theory, robotic rendezvous, distributed computing, filtering and control ...
- **some references**: [M. DeGroot '74, J. Tsitsiklis '84, ...]



Kuramoto model in \mathbb{T}^n :

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

- **oscillators** with phase $\theta_i \in \mathbb{T}$, frequency $\omega_i \in \mathbb{R}$, **complete** coupling
- **objective** is synchronization: $\theta_i(t) - \theta_j(t)$ bounded, $\dot{\theta}_i(t) - \dot{\theta}_j(t) \rightarrow 0$
- **application**: physics, biology, engineering, coupled neurons, Josephson junctions, motion coordination ...
- **some references**: [Y. Kuramoto '75, A. Winfree '80, ...]



Kuramoto model in \mathbb{T}^n :

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

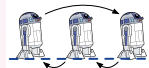
- degrees of synchronization:
 - 1 frequency entrainment
 - 2 phase locking
 - 3 phase synchronization
- known that
 - 1 for large K , frequency entrainment & phase locking
 - 2 additionally, for $\omega_i = \omega_j$, phase synchronization



Open problem in synchronization and transient stability in **power networks**: relation to underlying network state, parameters, and topology

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

Consensus Protocols:



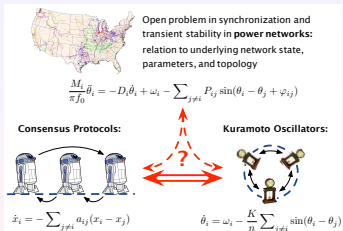
$$\dot{x}_i = - \sum_{j \neq i} a_{ij} (x_i - x_j)$$

Kuramoto Oscillators:



$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$





Possible connection has often been hinted at in the literature!

Power systems: [D. Subbarao et al., '01, G. Filatrella et al., '08, V. Fioriti et al., '09]

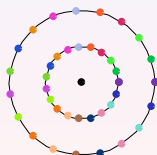
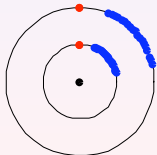
Networked control: [D. Hill et al., '06, M. Arcak, '07]

Dynamical systems: [H. Tanaka et al., '97]

From the swing equations to the Kuramoto model

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j) \implies D_i \dot{\theta}_i = \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$



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2 Singular perturbation analysis

(to relate power network and Kuramoto model)

3 Synchronization analysis (of non-uniform Kuramoto model)

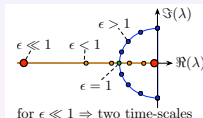
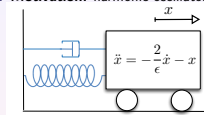
- 1 Main synchronization result
- 2 Sufficient condition (based on weakest lossless coupling)
- 3 Sufficient condition (based on lossless algebraic connectivity)
- 3 Further results

4 Conclusions

Singular Perturbation Analysis

Time-scale separation in power network model:

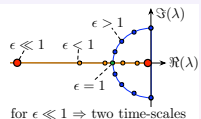
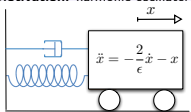
• Motivation: harmonic oscillator



• Singular perturbation analysis:

Time-scale separation in power network model:

- **Motivation:** harmonic oscillator

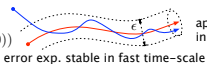


- **Singular perturbation analysis:**

full system $\begin{cases} \dot{x} = f(x, z) \\ \epsilon \dot{z} = g(x, z) \end{cases} \xrightarrow{\epsilon=0} \begin{cases} \dot{x} = f(x, h(x)) \\ z = h(x) \end{cases}$ reduced (slow) system
quasi-steady state

initial error:

$$z(0) \neq h(x(0))$$



approximation error
in slow time-scale: $\mathcal{O}(\epsilon)$

Singular Perturbation Analysis

Discussion of the assumption $\epsilon = \frac{M_{\max}}{\pi f_0 D_{\min}}$ sufficiently small:

- 1 physical interpretation: damping and sync on separate time-scales
- 2 classic assumption in literature on coupled oscillators: over-damped mechanical pendula and Josephson junctions
- 3 physical reality: with generator internal control effects $\epsilon \in \mathcal{O}(0.1)$
- 4 simulation studies show accurate approximation even for large ϵ
- 5 non-uniform Kuramoto model corresponds to reduced gradient system $\dot{\theta}_i = -\nabla_i U(\theta)^T$ used successfully in academia and industry since 1978

Time-scale separation in power network model:

- **power network model:**

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

- singular perturbation parameter: $\epsilon = \frac{M_{\max}}{\pi f_0 D_{\min}}$
- reduced system for $\epsilon = 0$ is a **non-uniform Kuramoto model**:

$$D_i \dot{\theta}_i = \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

Tikhonov's Theorem:

Assume the non-uniform Kuramoto model synchronizes exponentially. Then $\forall (\theta(0), \dot{\theta}(0))$ there exists $\epsilon^* > 0$ such that $\forall \epsilon < \epsilon^*$ and $\forall t \geq 0$
 $\theta_i(t)_{\text{power network}} - \theta_i(t)_{\text{non-uniform Kuramoto model}} = \mathcal{O}(\epsilon)$.

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 - 3 consensus and Kuramoto oscillators
- 2 Singular perturbation analysis
(to relate power network and Kuramoto model)
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 - 1 Main synchronization result
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Conditions on network parameters:

network connectivity > network's non-uniformity + network's losses,
and gap determines domain of attraction

1 Non-Uniform Kuramoto Model:

- ⇒ exponential synchronization: phase locking & frequency entrainment
- ⇒ for $\varphi_{ij} = 0$: explicit synchronization frequency & synchronization rates
- ⇒ for $\varphi_{ij} = 0$ & $\omega_i = \omega_j$: exponential phase synchronization

2 Power Network Model:

- ⇒ there exists ϵ sufficiently small such that for all $t \geq 0$

$$\theta_i(t)_{\text{power network}} - \theta_i(t)_{\text{non-uniform Kuramoto model}} = \mathcal{O}(\epsilon).$$

- ⇒ for ϵ and network losses φ_{ij} sufficiently small, $\mathcal{O}(\epsilon)$ error converges

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Non-uniform Kuramoto Model in \mathbb{T}^n :

$$D_i \dot{\theta}_i = \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

- **Non-uniformity** in network: $D_i, \omega_i, P_{ij}, \varphi_{ij}$
- **Directed coupling** between oscillator i and j :
 - coupling weights: $\frac{P_{ij}}{D_i} \neq \frac{P_{ji}}{D_j}$
 - coupling functions: $\sin(\theta_i - \theta_j + \varphi_{ij}) + \sin(\theta_j - \theta_i + \varphi_{ji}) \neq 0$
- **Phase shift** φ_{ij} induces lossless and lossy coupling:

$$P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij}) = P_{ij} \cos(\varphi_{ij}) \sin(\theta_i - \theta_j) + P_{ij} \sin(\varphi_{ij}) \cos(\theta_i - \theta_j)$$
- **Synchronization analysis** in multiple steps:
 - 1 phase locking: $\theta_i(t) - \theta_j(t)$ becomes bounded
 - 2 frequency entrainment: $\dot{\theta}_i(t) - \dot{\theta}_j(t) \rightarrow 0$
 - 3 phase synchronization: $\theta_i(t) - \theta_j(t) \rightarrow 0$

Non-uniform Kuramoto Model in \mathbb{T}^n - rewritten:

$$\dot{\theta}_i = \frac{\omega_i}{D_i} - \sum_{j \neq i} \frac{P_{ij}}{D_i} \cos(\varphi_{ij}) \sin(\theta_i - \theta_j) + \frac{P_{ij}}{D_i} \sin(\varphi_{ij}) \cos(\theta_i - \theta_j)$$

Condition (1) for synchronization:

Assume the graph induced by $P = P^T$ is complete and

$$n \underbrace{\frac{P_{\min}}{D_{\max}} \cos(\varphi_{\max})}_{\text{worst lossless coupling}} > \underbrace{\max_{\{i,j\}} \left(\frac{\omega_i}{D_i} - \frac{\omega_j}{D_j} \right)}_{\text{worst non-uniformity}} + \underbrace{\max_i \sum_j \frac{P_{ij}}{D_i} \sin(\varphi_{ij})}_{\text{worst lossy coupling}}$$

Gap determines the admissible initial lack of phase locking in a $\frac{\pi}{2}$ interval.

Synchronization of Non-Uniform Kuramoto Oscillators

Classic (uniform) Kuramoto Model in \mathbb{T}^n :

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

Condition (1) for synchronization:

$$K > \omega_{\max} - \omega_{\min}$$

Gap determines the admissible initial lack of phase locking in a $\frac{\pi}{2}$ interval.

Condition (1) strictly improves existing bounds on Kuramoto model:

[F. de Smet et al. '07, N. Chopra et al. '09, G. Schmidt et al. '09, A. Jadbabaie et al. '04, J.L. van Hemmen et al. '93].

Necessary condition for sync of n oscillators: $K > \frac{n}{2(n-1)}(\omega_{\max} - \omega_{\min})$

[J.L. van Hemmen et al. '93, A. Jadbabaie et al. '04, N. Chopra et al. '09]

Synchronization of Non-Uniform Kuramoto Oscillators

Theorem: Phase locking and frequency entrainment (1)

Non-uniform Kuramoto with complete $P = P^T$

Assume minimal coupling larger than a critical value, i.e.,

$$P_{\min} > P_{\text{critical}} := \frac{D_{\max}}{n \cos(\varphi_{\max})} \left(\max_{\{i,j\}} \left(\frac{\omega_i}{D_i} - \frac{\omega_j}{D_j} \right) + \max_i \sum_j \frac{P_{ij}}{D_i} \sin(\varphi_{ij}) \right)$$

Define $\delta = \frac{\pi}{2} - \arccos(\cos(\varphi_{\max}) \frac{P_{\min}}{D_{\max}})$ and **set of locked phases**

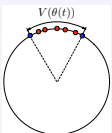
$$\Delta(\delta) := \{ \theta \in \mathbb{T}^n \mid \max_{\{i,j\}} |\theta_i - \theta_j| \leq \delta \}$$

Then

- 1) **phase locking:** the set $\Delta(\delta)$ is positively invariant
- 2) **frequency entrainment:** $\forall \theta(0) \in \Delta(\delta)$ the frequencies $\dot{\theta}_i(t)$ synchronize exponentially to some frequency $\dot{\theta}_\infty \in [\dot{\theta}_{\min}(0), \dot{\theta}_{\max}(0)]$

Main proof ideas:

- 1 Phase locking in $\Delta(\delta) \Leftrightarrow$ arc-length $V(\theta(t))$ is non-increasing



$$\Leftrightarrow \begin{cases} V(\theta(t)) = \max\{|\theta_i(t) - \theta_j(t)| \mid i, j \in \{1, \dots, n\}\} \\ D^+ V(\theta(t)) \stackrel{!}{\leq} 0 \end{cases}$$

~ contraction property from consensus literature:
[D. Bertsekas et al. '94, L. Moreau '04 & '05,
Z. Lin et al. '08, ...]

- 2 Frequency entrainment in $\Delta(\delta) \Leftrightarrow$ consensus protocol in \mathbb{R}^n

$$\ddot{\theta}_i = - \sum_{j \neq i} a_{ij}(t) (\dot{\theta}_i - \dot{\theta}_j),$$

$$\text{where } a_{ij}(t) = \frac{P_{ij}}{D_i} \cos(\theta_i(t) - \theta_j(t) + \varphi_{ij}) > 0 \text{ for all } t \geq 0$$

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Synchronization of Non-Uniform Kuramoto Oscillators

Non-uniform Kuramoto Model in \mathbb{T}^n - rewritten:

$$\dot{\theta}_i = \frac{\omega_i}{D_i} - \sum_{j \neq i} \frac{P_{ij}}{D_i} \cos(\varphi_{ij}) \sin(\theta_i - \theta_j) + \frac{P_{ij}}{D_i} \sin(\varphi_{ij}) \cos(\theta_i - \theta_j)$$

Condition (2) for synchronization:

Assume the graph induced by $P = P^T$ is **connected** with unweighted Laplacian L and weighted Laplacian $L(P_{ij} \cos(\varphi_{ij}))$ and

$$\underbrace{\lambda_2(L(P_{ij} \cos(\varphi_{ij})))}_{\text{lossless connectivity}} > \underbrace{f(D_i)}_{\text{non-uniform } D_i\text{'s}} \cdot \underbrace{(1/\cos(\varphi_{\max}))}_{\text{necessary phase locking}} \times \underbrace{\left(\left\| \left[\dots, \frac{\omega_i}{D_i} - \frac{\omega_j}{D_j}, \dots \right] \right\|_2 \right)}_{\text{non-uniformity}} + \underbrace{\left(\sqrt{\lambda_{\max}(L)} \left\| \left[\dots, \sum_j \frac{P_{ij}}{D_i} \sin(\varphi_{ij}), \dots \right] \right\|_2 \right)}_{\text{lossy coupling}}$$

Gap determines the admissible initial lack of phase locking in a π interval.

Synchronization of Non-Uniform Kuramoto Oscillators

Classic (uniform) Kuramoto Model in \mathbb{T}^n :

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

Condition (2) for synchronization:

$$K > \left\| [\dots, \omega_i - \omega_j, \dots] \right\|_2$$

Gap determines the admissible initial lack of phase locking in a π interval.

Condition (2) corresponds to the bound in [N. Chopra et al. '09].

Theorem: Phase locking and frequency entrainment (2)

Assume graph induced by $P = P^T$ is connected with unweighted Laplacian L , incidence matrix H , and weighted Laplacian $L(P_{ij} \cos(\varphi_{ij}))$. Assume algebraic connectivity is larger than a critical value, i.e.,

$$\lambda_2(L(P_{ij} \cos(\varphi_{ij}))) > \lambda_{\text{critical}} := \frac{\|HD^{-1}\omega\|_2 + \sqrt{\lambda_{\max}(L)} \left\| \left[\dots, \sum_j \frac{P_{ij}}{D_i} \sin(\varphi_{ij}), \dots \right] \right\|_2}{\cos(\varphi_{\max}) (\kappa/n) \mu \min_{\{i,j\}} \{D_{i,j}\}}$$

where $\kappa := \sum_{k=1}^n \frac{1}{D_{i,k}}$, $\mu := \sqrt{\min_{i,j} \{D_i D_j\} / \max_{i,j} \{D_i D_j\}}$

Define $\phi_{\min} \in (0, \frac{\pi}{2})$ by $\text{sinc}(\pi - \phi_{\min}) = (2/\pi) \lambda_{\text{critical}} / \lambda_2(L(P_{ij} \cos(\varphi_{ij})))$.

- phase locking:** $\forall \|H\theta(0)\|_2 \leq \mu(\pi - \phi_{\min})$, there is $T \geq 0$ such that $\|H\theta(t)\|_2 < \frac{\pi}{2} - \varphi_{\max}$ for all $t > T$
- frequency entrainment:** $\forall \|H\theta(0)\|_2 \leq \mu(\pi - \phi_{\min})$ the frequencies $\dot{\theta}_i(t)$ synchronize exponentially to some frequency $\dot{\theta}_{\infty} \in [\dot{\theta}_{\min}(0), \dot{\theta}_{\max}(0)]$

Main proof ideas:

- Phase locking** in $\Delta(\delta)$ via ultimate boundedness arguments

$$\|H\theta(0)\| < \mu(\pi - \phi) \quad \theta(t)$$

$$\|H\theta(T)\| < \pi/2$$

$$-\varphi_{\max} \quad t=0 \quad t=T$$

$$\dot{\theta}(\theta) < 0$$

$$\dot{\theta}(\theta) = 0$$

$$\dot{\theta}(\theta) > 0$$

$$\mathcal{W}(\theta) = \frac{1}{2} \sum_{\{i,j\}} \frac{1}{D_{\neq\{i,j\}}} |\theta_i - \theta_j|^2$$

- Frequency entrainment** for $t > T \Leftrightarrow$ consensus protocol in \mathbb{R}^n

$$\ddot{\theta}_i = - \sum_{j \neq i} a_{ij}(t) (\dot{\theta}_i - \dot{\theta}_j),$$

$$\text{where } a_{ij}(t) = \frac{P_{ij}}{D_i} \cos(\theta_i(t) - \theta_j(t) + \varphi_{ij}) > 0 \text{ for all } t > T$$

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 - synchronization and transient stability
 - power network model
 - consensus and Kuramoto oscillators
- Singular perturbation analysis
(to relate power network and Kuramoto model)
- Synchronization analysis (of non-uniform Kuramoto model)
 - Main synchronization result
 - Sufficient condition (based on weakest lossless coupling)
 - Sufficient condition (based on lossless algebraic connectivity)
 - Further results
- Conclusions

Synchronization of Non-Uniform Kuramoto Oscillators
Theorem: A refined result on frequency entrainment

Assume graph induced by P has **globally reachable node** and there exists $\delta \in (0, \frac{\pi}{2})$ such that the phases are locked in the set $\Delta(\delta)$

If $P = P^T$ & $\varphi_{ij} = 0$ for all $i, j \in \{1, \dots, n\}$, then $\forall \theta(0) \in \Delta(\delta)$ the frequencies $\dot{\theta}_i(t)$ synchronize exp. to the weighted mean frequency

$$\Omega_c = \frac{1}{\sum_i D_i} \sum_i D_i \omega_i$$

and the exponential synchronization rate is no worse than

$$\lambda_{fe} = - \underbrace{\lambda_2(L(P_{ij}))}_{\text{connectivity}} \underbrace{\sin(\delta)}_{\Delta(\delta)} \underbrace{\cos(\angle(D\mathbf{1}, \mathbf{1}))^2}_{1 \neq D\mathbf{1}} / \underbrace{D_{\max}}_{\text{slowest}}$$

Theorem: A result on phase synchronization

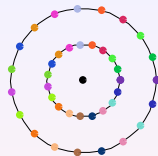
Assume the graph induced by P has a globally reachable node, and $\varphi_{ij} = 0$ and $\frac{\omega_i}{D_i} = \frac{\omega_j}{D_j}$ for all $i, j \in \{1, \dots, n\}$. Let $\phi \in (0, \pi]$.

For the non-uniform Kuramoto model,

- $\forall \theta(0) \in \{\theta \in \mathbb{T}^n : \max_{\{i,j\}} |\theta_i - \theta_j| < \pi - \phi\}$ the phases $\theta_i(t)$ synchronize exponentially; and
- if $P = P^T$, $\forall \|H\theta(0)\|_2 \leq \mu(\pi - \phi)$ the phases $\theta_i(t)$ synchronize exponentially at a rate no worse than

$$\lambda_{\text{ps}} = - \underbrace{(\kappa/n) \min_{\{i,j\}} \{D_{\neq\{i,j\}}\}}_{\text{weighting of } D_i} \underbrace{\text{sinc}(\pi - \phi)}_{\theta(0)} \underbrace{\lambda_2(L(P_{ij}))}_{\text{connectivity}}$$

Result can be reduced to [A. Jadbabaie et al. '04].

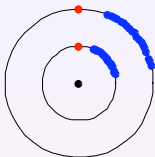
**Simulation data:**

- worst-case initial phase-differences: $\theta_i(0)$ in splay state
- $\epsilon = 0.12s$ is small
- strongly** non-uniform network

⇒ sufficient conditions for synchronization are **not satisfied**

Result: singular perturbation analysis is accurate ✓
both models synchronize ✓

Simulation Studies

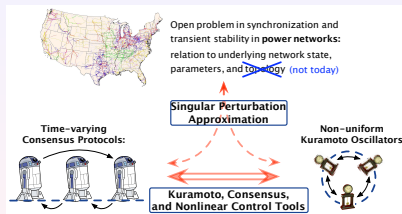
**Simulation data:**

- initial phases mostly clustered besides red phasor
- $\epsilon = 0.6s$ is **large**
- non-uniform network

⇒ sufficient conditions for synchronization are **satisfied**

Result: singular perturbation analysis is accurate ✓
both models synchronize ✓

Conclusions

Summary:**Future Work:**

- relation to network topology, clustering and scalability
- synchronization in optimal power flow problems